

Digital Design with the Verilog HDL

Chapter 8 Datapath & Controller

Binh Tran-Thanh

Department of Computer Engineering
Faculty of Computer Science and Engineering
Ho Chi Minh City University of Technology

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Digital Systems Classification

Control-dominated

- Reactive systems responding to external events

Data-dominated

- High throughput data computation and transport

⇒ Sequential machines are classified and portioned into datapath units and control units



What are controller, Datapath, and its example

Control units

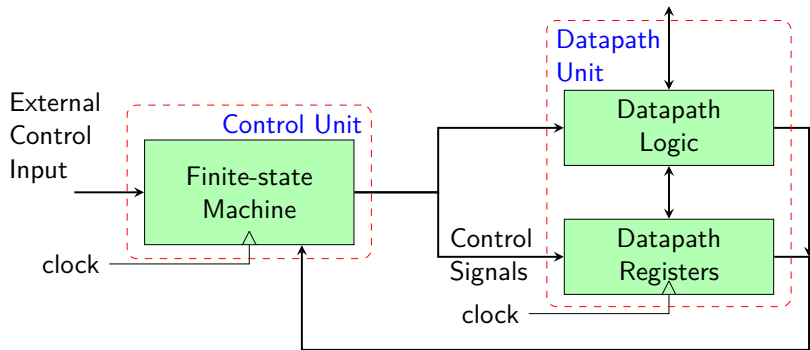
- FSM coordinating the execution of instructions that perform operation on the datapath

Datapath units

- Computational resources (ALU, register,...)
- Adder, multiplier
- DSP
- ...



State-machine Controller and Datapath



Controller and Datapath Modelling

Modelling

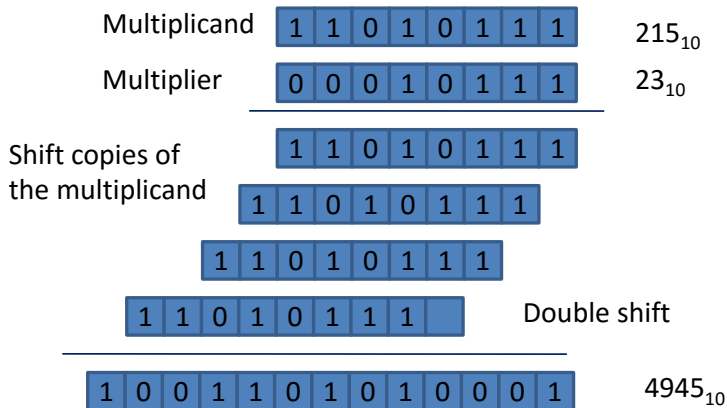
- Controller:
 - State transition graphs
 - Algorithmic-state machine (ASM)
- Datapath:
 - Data flow graph

Functional

- Controller:
 - Generate signals: load, read, clear, and shift storage registers
 - Control the operations: ALU, complex datapath units
- Datapath:
 - Perform operations



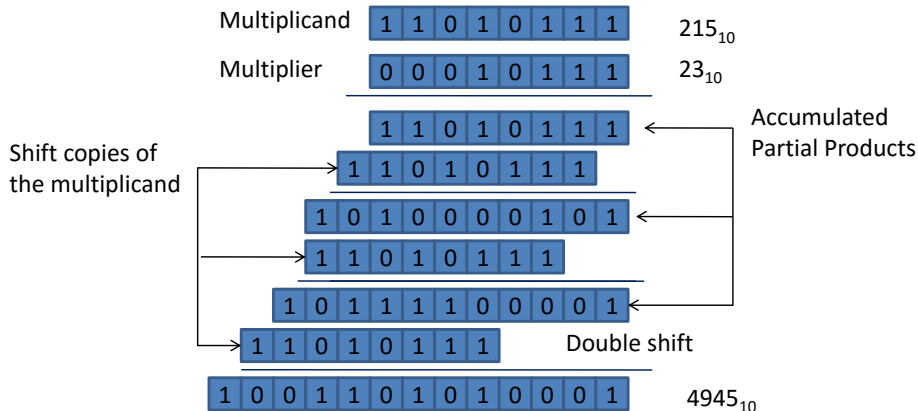
Combinational Binary Multiplier



- A combinational Circuit can be developed to implement the product
- Require hardware with multiple adders for each column
- Ordinary adder operates on only two words at a time



Combinational Binary Multiplier

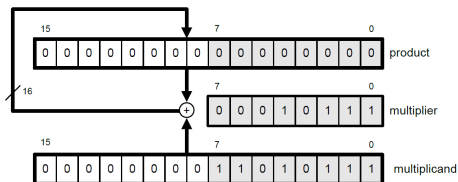
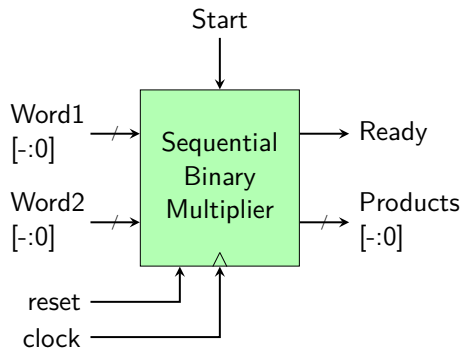


- Combinational Binary Multiplier operate fast, but require a significant amount of silicon area

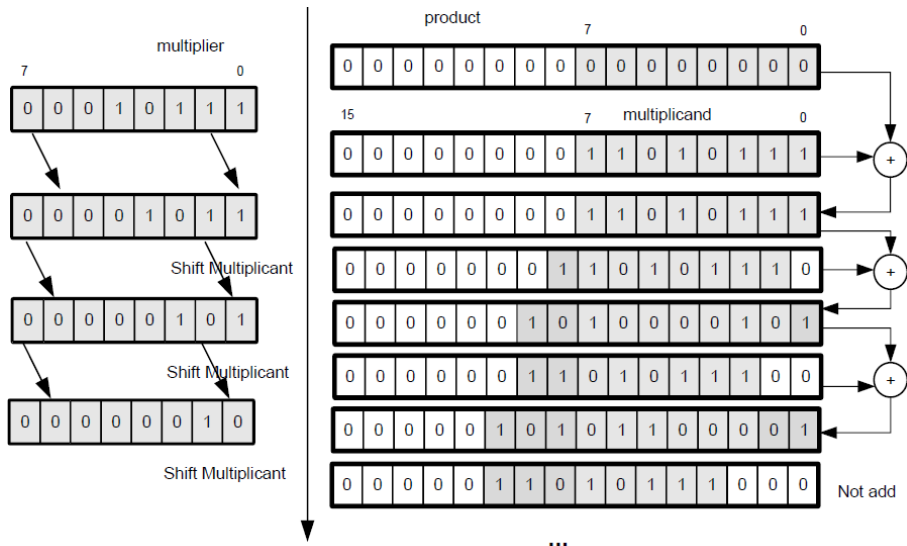


Sequential Binary Multiplier

- Choose a datapath architecture
- Design state machine for controller

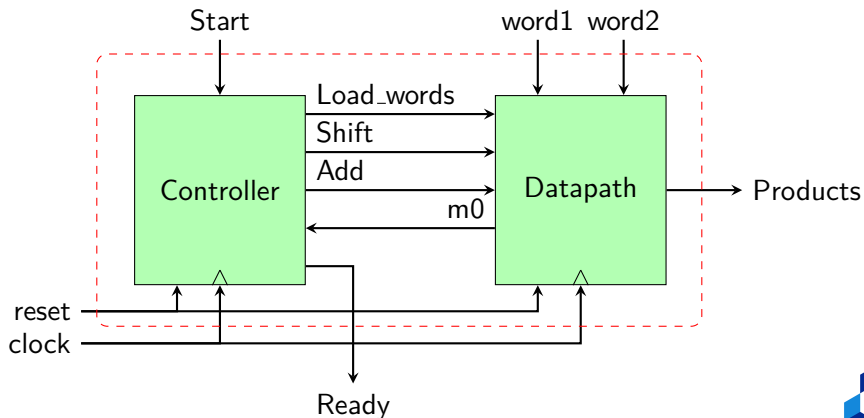


Register transfers

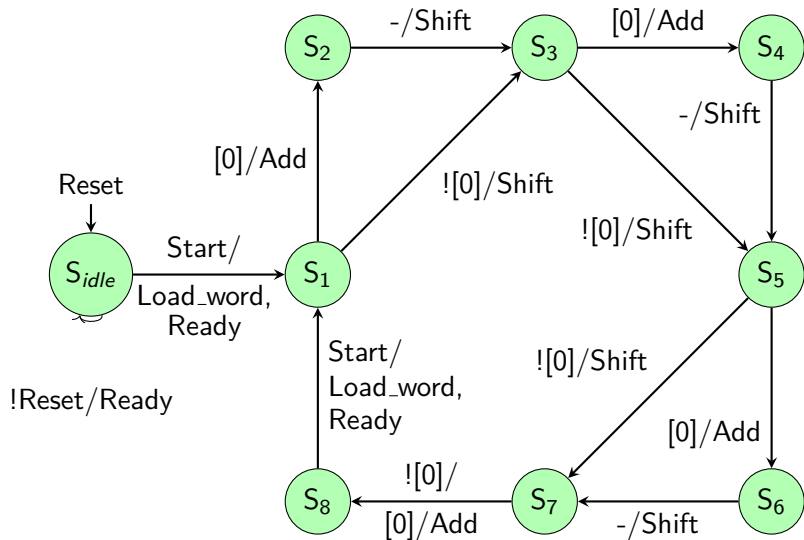


Structural Units

- Top-level module: Multiplier_STG_0
- m0: LSB of Multiplier, used to control state transaction



STGs for 4-bit Seq. Multiplier



Module Declaration

```
module Multiplier_STG_0 (product, Ready, word1, word2,  
    Start, clk, rst);  
    parameter L_WORD= 4; // Datapathsize  
    output [2*L_WORD-1: 0] product;  
    output Ready;  
    input [L_WORD -1: 0] word1, word2;  
    input Start, clk, rst;  
    wire m0, Load_words, Shift;  
  
    Datapath M1(product, m0, word1, word2, Load_words, Shift,  
        Add, clk, rst);  
    Controller M2(Load_words, Shift, Add, Ready, m0, Start,  
        clk, rst);  
endmodule
```



Controller (1/2)

```
module Controller (Load_words, Shift, Add, Ready, m0, Start
    , clk, rst);
    output Load_words, Shift, Add, Ready;
    input m0, Start, clk, rst;

    parameter L_WORD= 4; // Datapath size
    parameter L_STATE= 4; // State size
    parameter S_idle= 0, S_1 = 1, S_2 = 2, S_3 = 3;
    parameter S_4 = 4, S_5 = 5, S_6 = 6, S_7 = 7, S_8 = 8;

    reg Load_words, Shift, Add;
    reg[L_STATE-1: 0] state, next_state;

    wire Ready = ((state == S_idle) && !rst) ||
        (state == S_8);

    /* State transitions */
    always @ (posedge clk or posedge rst)
    __if(rst) state <= S_idle;
    __else state <= next_state;
```



Controller(2/2)

```
/*Next state and control logic */
always @ (state or Start or m0) begin
    Load_words= 0; Shift = 0; Add = 0;
    case(state)
        S_idle: if(Start) begin Load_words=1; next_state=S_1;
            end
                else next_state= S_idle;
        S_1:if(m0) begin Add = 1; next_state= S_2; end
            else begin Shift = 1; next_state= S_3; end
        S_2: begin Shift = 1; next_state= S_3; end
        S_3: if(m0) begin Add = 1; next_state= S_4; end
            else begin Shift = 1; next_state= S_5; end
        S_4: beginShift = 1; next_state= S_5; end
        S_5: if(m0) begin Add = 1; next_state= S_6; end
            else begin Shift = 1; next_state= S_7; end
        S_6: beginShift = 1; next_state= S_7; end
        S_7: if(m0) begin Add = 1; next_state= S_8; end
            else begin next_state= S_8; end
        S_8: if(Start) beginLoad_words= 1; next_state= S_1; end
            else next_state= S_8;
        default:next_state= S_idle;
    endcase
end
endmodule
```



Datapath

```
module Datapath(product, m0, word1, word2, Load_words,
    Shift, Add, clk, rst);
    parameter L_WORD= 4;
    output [2*L_WORD-1: 0] product;
    output m0;
    input [L_WORD-1: 0] word1, word2;
    input Load_words, Shift, Add, clk, rst;
    reg [2*L_WORD-1: 0] product, multiplicand;
    reg [L_WORD-1: 0] multiplier;
    wire m0 = multiplier[0];

    always @ (posedge clk or posedge rst) begin
        if (rst) begin multiplier <= 0;
            multiplicand <= 0; product <= 0; end
        else if (Load_words) begin multiplicand <= word1;
            multiplier <= word2; product <= 0; end
        else if (Shift) begin multiplier <= multiplier >> 1;
            multiplicand <= multiplicand << 1; end
        else if (Add) begin product <= product+ multiplicand;
            end
        end
    endmodule
```

